

Tree-Like Justification Systems are Consistent

Simon Marynissen^{1,2} and **Bart Bogaerts**²

¹*KU Leuven* and ²*Vrije Universiteit Brussel*

International Conference on Logic Programming
August 3rd, 2022



ARTIFICIAL
INTELLIGENCE
RESEARCH GROUP

OUR RESULT

Theorem

Every tree-like justification system is consistent.

OUR RESULT

Theorem

Every tree-like justification system is consistent.

This result will be important for the next talk (“On Nested Justification Systems”).

OUTLINE

1. Justification Theory: Motivation & Definitions
2. Two Flavours of Justifications
3. The Consistency Problem
4. The Proof
5. Conclusion

OUTLINE

1. Justification Theory: Motivation & Definitions
2. Two Flavours of Justifications
3. The Consistency Problem
4. The Proof
5. Conclusion

JUSTIFICATION THEORY: A UNIFYING FRAMEWORK

Unification of formalisms

- ▶ Logic Programming
- ▶ Abstract Argumentation
- ▶ Nested least and greatest fixpoint definitions

JUSTIFICATION THEORY: A UNIFYING FRAMEWORK

Unification of formalisms

- ▶ Logic Programming
- ▶ Abstract Argumentation
- ▶ Nested least and greatest fixpoint definitions

Simple and unified way of defining and studying semantics

- ▶ Stable
- ▶ Well-founded
- ▶ Supported
- ▶ Kripke-Kleene

The **only** thing to define is an evaluation of **branches**

JUSTIFICATION THEORY: A UNIFYING FRAMEWORK

Unification of formalisms

- ▶ Logic Programming
- ▶ Abstract Argumentation
- ▶ Nested least and greatest fixpoint definitions

Simple and unified way of defining and studying semantics

- ▶ Stable
- ▶ Well-founded
- ▶ Supported
- ▶ Kripke-Kleene

The **only** thing to define is an evaluation of **branches**

Core idea: semantics is defined in terms of **explanations** why facts hold.

JUSTIFICATION THEORY: A UNIFYING FRAMEWORK

Unification of formalisms

- ▶ Logic Programming
- ▶ Abstract Argumentation
- ▶ Nested least and greatest fixpoint definitions

Simple and unified way of defining and studying semantics

- ▶ Stable
- ▶ Well-founded
- ▶ Supported
- ▶ Kripke-Kleene

The **only** thing to define is an evaluation of **branches**

Core idea: semantics is defined in terms of **explanations** why facts hold.
Not just relevant for theory; justifications show up in unexpected places

DEFINITIONS: JUSTIFICATION FRAMES

Definition

A **justification frame** \mathbb{JF} is a tuple $\langle \mathbb{F}, \mathbb{F}_d, R \rangle$ with:

fact space \mathbb{F} with $\mathcal{L} = \{\mathbf{t}, \mathbf{f}, \mathbf{u}\} \subseteq \mathbb{F}$.

Involution \sim on \mathbb{F}

(with $\sim \mathbf{t} = \mathbf{f}$, $\sim \mathbf{f} = \mathbf{t}$, $\sim \mathbf{u} = \mathbf{u}$)

defined facts $\mathbb{F}_d \subseteq \mathbb{F} \setminus \mathcal{L}$; $\sim \mathbb{F}_d = \mathbb{F}_d$.

rules $R \subseteq \mathbb{F}_d \times 2^{\mathbb{F}}$

Example

$$\mathbb{F} = \{p, \sim p, q, \sim q, r, \sim r, s, \sim s, \mathbf{t}, \mathbf{f}, \mathbf{u}\}$$

$$\mathbb{F}_d = \{p, \sim p, q, \sim q, r, \sim r\}$$

$$p \leftarrow \sim q$$

$$q \leftarrow \sim p$$

$$p \leftarrow s, \sim r$$

$$r \leftarrow r$$

DEFINITIONS: JUSTIFICATION FRAMES

Definition

A **justification frame** \mathbb{JF} is a tuple $\langle \mathbb{F}, \mathbb{F}_d, R \rangle$ with:

fact space \mathbb{F} with $\mathcal{L} = \{\mathbf{t}, \mathbf{f}, \mathbf{u}\} \subseteq \mathbb{F}$.

Involution \sim on \mathbb{F}

(with $\sim \mathbf{t} = \mathbf{f}$, $\sim \mathbf{f} = \mathbf{t}$, $\sim \mathbf{u} = \mathbf{u}$)

defined facts $\mathbb{F}_d \subseteq \mathbb{F} \setminus \mathcal{L}$; $\sim \mathbb{F}_d = \mathbb{F}_d$.

rules $R \subseteq \mathbb{F}_d \times 2^{\mathbb{F}}$

Example

$$\mathbb{F} = \{p, \sim p, q, \sim q, r, \sim r, s, \sim s, \mathbf{t}, \mathbf{f}, \mathbf{u}\}$$

$$\mathbb{F}_d = \{p, \sim p, q, \sim q, r, \sim r\}$$

Complementation:

$$\begin{array}{ll} p \leftarrow \sim q & \sim p \leftarrow q, r \\ q \leftarrow \sim p & \sim p \leftarrow q, \sim s \\ p \leftarrow s, \sim r & \sim q \leftarrow p \\ r \leftarrow r & \sim r \leftarrow \sim r \end{array}$$

DEFINITIONS: JUSTIFICATIONS

$$p \leftarrow \sim q$$

$$q \leftarrow \sim p$$

$$p \leftarrow s, \sim r$$

$$r \leftarrow r$$

$$\sim p \leftarrow q, r$$

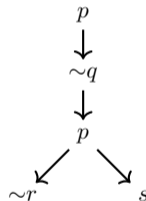
$$\sim p \leftarrow q, \sim s$$

$$\sim q \leftarrow p$$

$$\sim r \leftarrow \sim r$$

Definition

Let $\mathbb{JF} = \langle \mathbb{F}, \mathbb{F}_d, R \rangle$ be a justification frame. A (tree-like) justification J in \mathbb{JF} is a labeled tree such that the set of children of each node is a case (rule) in R for that node.



DEFINITIONS: JUSTIFICATIONS

Definition

Let $\mathbb{JF} = \langle \mathbb{F}, \mathbb{F}_d, R \rangle$ be a justification frame. A (tree-like) justification J in \mathbb{JF} is a labeled tree such that the set of children of each node is a case (rule) in R for that node.

J is **locally complete** if all leaves are open

$$p \leftarrow \sim q$$

$$q \leftarrow \sim p$$

$$p \leftarrow s, \sim r$$

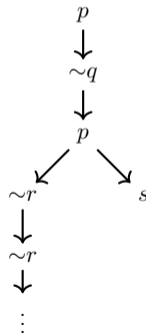
$$r \leftarrow r$$

$$\sim p \leftarrow q, r$$

$$\sim p \leftarrow q, \sim s$$

$$\sim q \leftarrow p$$

$$\sim r \leftarrow \sim r$$



DEFINITIONS: BRANCH EVALUATION

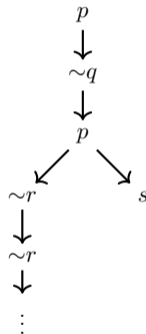
Definition

A **branch evaluation** \mathcal{B} maps every branch (sequence of facts) to an element of \mathbb{F} .

A **justification system** \mathbb{JS} is a tuple $\langle \mathbb{F}, \mathbb{F}_d, R, \mathcal{B} \rangle$.

The **stable** branch evaluation \mathcal{B}_{st} maps

- ▶ finite branches to their last element
- ▶ infinite branches with positive tail to \mathbf{f}
- ▶ infinite branches with negative tail to \mathbf{t}
- ▶ infinite branches with mixed tail to the element of the first sign switch



DEFINITIONS: BRANCH EVALUATION

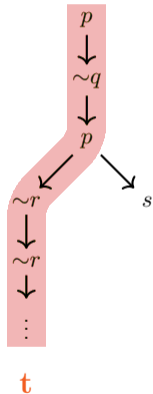
Definition

A **branch evaluation** \mathcal{B} maps every branch (sequence of facts) to an element of \mathbb{F} .

A **justification system** \mathbb{JS} is a tuple $\langle \mathbb{F}, \mathbb{F}_d, R, \mathcal{B} \rangle$.

The **stable** branch evaluation \mathcal{B}_{st} maps

- ▶ finite branches to their last element
- ▶ infinite branches with positive tail to \mathbf{f}
- ▶ **infinite branches with negative tail to \mathbf{t}**
- ▶ infinite branches with mixed tail to the element of the first sign switch



DEFINITIONS: BRANCH EVALUATION

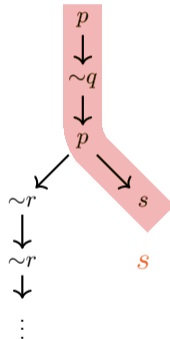
Definition

A **branch evaluation** \mathcal{B} maps every branch (sequence of facts) to an element of \mathbb{F} .

A **justification system** \mathbb{JS} is a tuple $\langle \mathbb{F}, \mathbb{F}_d, R, \mathcal{B} \rangle$.

The **stable** branch evaluation \mathcal{B}_{st} maps

- ▶ finite branches to their last element
- ▶ infinite branches with positive tail to \mathbf{f}
- ▶ infinite branches with negative tail to \mathbf{t}
- ▶ infinite branches with mixed tail to the element of the first sign switch



DEFINITIONS: BRANCH EVALUATION

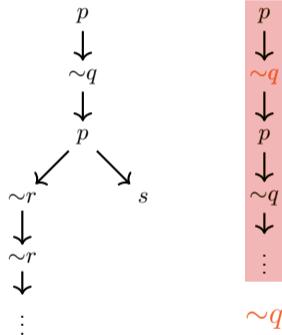
Definition

A **branch evaluation** \mathcal{B} maps every branch (sequence of facts) to an element of \mathbb{F} .

A **justification system** \mathbb{JS} is a tuple $\langle \mathbb{F}, \mathbb{F}_d, R, \mathcal{B} \rangle$.

The **stable** branch evaluation \mathcal{B}_{st} maps

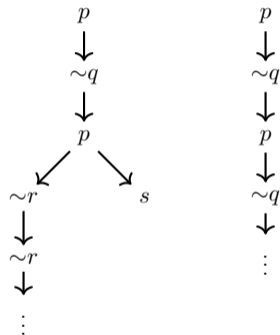
- ▶ finite branches to their last element
- ▶ infinite branches with positive tail to \mathbf{f}
- ▶ infinite branches with negative tail to \mathbf{t}
- ▶ infinite branches with mixed tail to the element of the first sign switch



DEFINITIONS: BRANCH EVALUATION (2)

The **well-founded** branch evaluation \mathcal{B}_{wf} maps

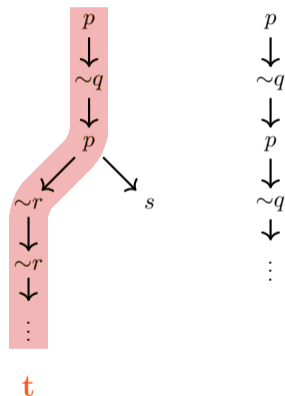
- ▶ finite branches to their last element
- ▶ infinite branches with positive tail to **f**
- ▶ infinite branches with negative tail to **t**
- ▶ infinite branches with mixed tail to **u**



DEFINITIONS: BRANCH EVALUATION (2)

The **well-founded** branch evaluation \mathcal{B}_{wf} maps

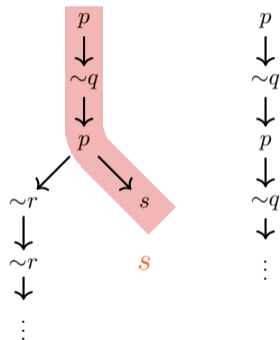
- ▶ finite branches to their last element
- ▶ infinite branches with positive tail to **f**
- ▶ **infinite branches with negative tail to t**
- ▶ infinite branches with mixed tail to **u**



DEFINITIONS: BRANCH EVALUATION (2)

The **well-founded** branch evaluation \mathcal{B}_{wf} maps

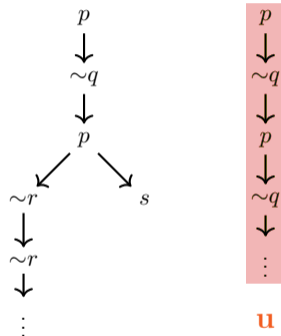
- ▶ finite branches to their last element
- ▶ infinite branches with positive tail to **f**
- ▶ infinite branches with negative tail to **t**
- ▶ infinite branches with mixed tail to **u**



DEFINITIONS: BRANCH EVALUATION (2)

The **well-founded** branch evaluation \mathcal{B}_{wf} maps

- ▶ finite branches to their last element
- ▶ infinite branches with positive tail to **f**
- ▶ infinite branches with negative tail to **t**
- ▶ **infinite branches with mixed tail to u**



DEFINITIONS: INTERPRETATIONS

Definition

An **interpretation** I maps each fact in \mathbb{F} to a truth value (in \mathcal{L}) and

- ▶ Commutes with negation:

$$I(\sim x) = \sim I(x)$$

- ▶ Identity on \mathcal{L}

$$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$$

DEFINITIONS: INTERPRETATIONS

Definition

An **interpretation** I maps each fact in \mathbb{F} to a truth value (in \mathcal{L}) and

- ▶ Commutes with negation:

$$I(\sim x) = \sim I(x)$$

- ▶ Identity on \mathcal{L}

$$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$$

And implicitly: $I(\sim p) = \mathbf{f}, I(\sim q) = \mathbf{t},$
 $I(r) = \mathbf{f}, I(s) = \mathbf{t},$
 $I(\mathbf{t}) = \mathbf{t}, I(\mathbf{f}) = \mathbf{f}, I(\mathbf{u}) = \mathbf{u}$

DEFINITIONS: SUPPORTED VALUE

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Definition

The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

DEFINITIONS: SUPPORTED VALUE

Definition

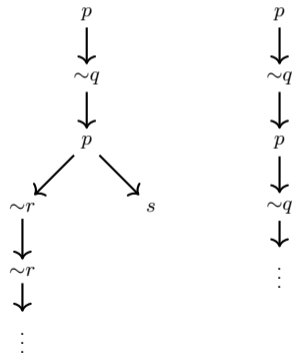
The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



DEFINITIONS: SUPPORTED VALUE

Definition

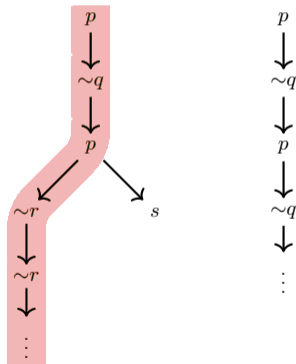
The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



$I(\mathbf{t}) = \mathbf{t}$

DEFINITIONS: SUPPORTED VALUE

Definition

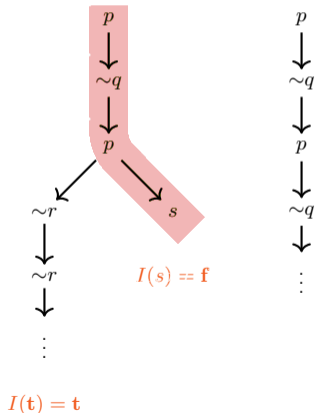
The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



DEFINITIONS: SUPPORTED VALUE

Definition

The **value** of node x in J under I is the value of the worst branch starting in x :

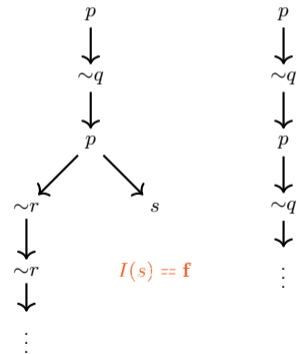
$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}

$$\min(\mathbf{t}, \mathbf{f}) = \mathbf{f}$$



$$I(\mathbf{t}) = \mathbf{t}$$

DEFINITIONS: SUPPORTED VALUE

Definition

The **value** of node x in J under I is the value of the worst branch starting in x :

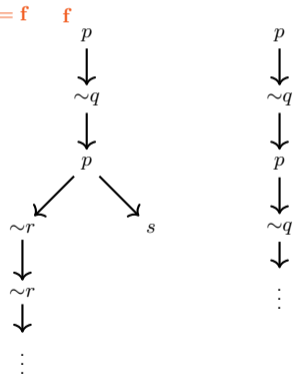
$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}

$\min(\mathbf{t}, \mathbf{f}) = \mathbf{f}$



DEFINITIONS: SUPPORTED VALUE

Definition

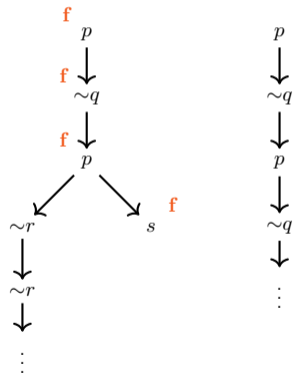
The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



DEFINITIONS: SUPPORTED VALUE

Definition

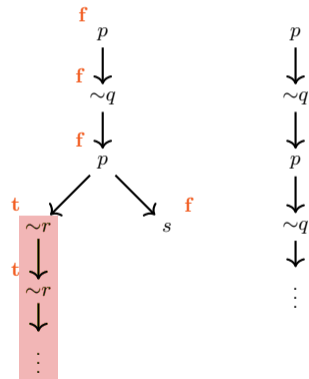
The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



DEFINITIONS: SUPPORTED VALUE

Definition

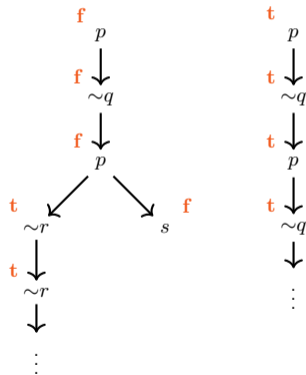
The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



DEFINITIONS: SUPPORTED VALUE

Definition

The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

Definition

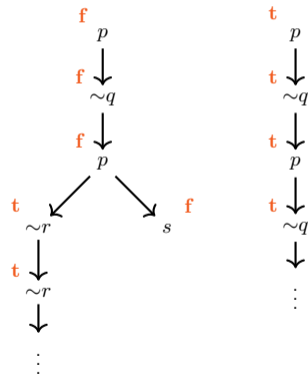
The **supported value** of x under I is the value of the best justification for x :

$$\text{SV}_{\mathcal{B}}(x, I) = \max_{J \in \mathcal{J}(x)} \text{val}(J, x, I)$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



DEFINITIONS: SUPPORTED VALUE

Definition

The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

Definition

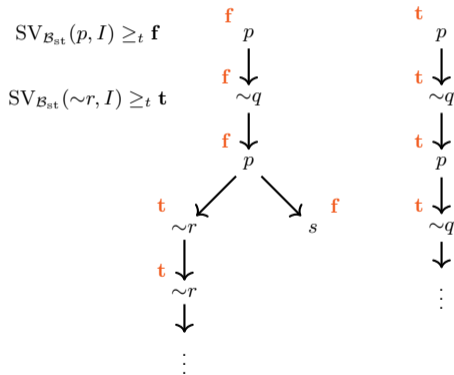
The **supported value** of x under I is the value of the best justification for x :

$$\text{SV}_{\mathcal{B}}(x, I) = \max_{J \in \mathcal{J}(x)} \text{val}(J, x, I)$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



DEFINITIONS: SUPPORTED VALUE

Definition

The **value** of node x in J under I is the value of the worst branch starting in x :

$$\text{val}_{\mathcal{B}}(J, x, I) = \min_{\mathbf{b} \in B_J(x)} I(\mathcal{B}(\mathbf{b}))$$

Definition

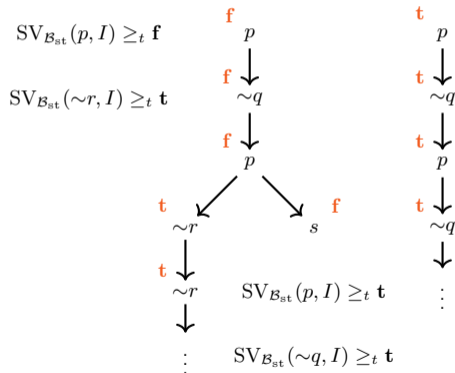
The **supported value** of x under I is the value of the best justification for x :

$$SV_{\mathcal{B}}(x, I) = \max_{J \in \mathcal{J}(x)} \text{val}(J, x, I)$$

order: $\mathbf{f} \leq_t \mathbf{u} \leq_t \mathbf{t}$

Example

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$ using \mathcal{B}_{st}



DEFINITIONS: MODEL

Definition

An **interpretation** I is a \mathcal{B} -model if

$$I(x) = SV_{\mathcal{B}}(x, I)$$

for all defined facts x .

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{t}, I(s) = \mathbf{f}$. I is **not** a \mathcal{B}_{st} -model of

$$\begin{array}{ll} p \leftarrow \sim q & \sim p \leftarrow q, r \\ q \leftarrow \sim p & \sim p \leftarrow q, \sim s \\ p \leftarrow s, \sim r & \sim q \leftarrow p \\ r \leftarrow r & \sim r \leftarrow \sim r \end{array}$$

r only has one justification.

$$\mathbf{t} = I(r) \neq SV_{\mathcal{B}_{\text{st}}}(r, I) = \mathbf{f}$$

DEFINITIONS: MODEL

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{f}, I(s) = \mathbf{f}.$
 I is a \mathcal{B}_{st} -model of

$$p \leftarrow \sim q$$

$$\sim p \leftarrow q, r$$

$$q \leftarrow \sim p$$

$$\sim p \leftarrow q, \sim s$$

$$p \leftarrow s, \sim r$$

$$\sim q \leftarrow p$$

$$r \leftarrow r$$

$$\sim r \leftarrow \sim r$$

Definition

An **interpretation** I is a \mathcal{B} -model if

$$I(x) = \text{SV}_{\mathcal{B}}(x, I)$$

for all defined facts x .

DEFINITIONS: MODEL

$I(p) = \mathbf{t}, I(q) = \mathbf{f}, I(r) = \mathbf{f}, I(s) = \mathbf{f}.$
 I is a \mathcal{B}_{st} -model of

$$p \leftarrow \sim q$$

$$\sim p \leftarrow q, r$$

$$q \leftarrow \sim p$$

$$\sim p \leftarrow q, \sim s$$

$$p \leftarrow s, \sim r$$

$$\sim q \leftarrow p$$

$$r \leftarrow r$$

$$\sim r \leftarrow \sim r$$

Definition

An **interpretation** I is a \mathcal{B} -model if

$$I(x) = \text{SV}_{\mathcal{B}}(x, I)$$

for all defined facts x .

$$\begin{array}{c} \sim r \\ \downarrow \\ \sim r \\ \downarrow \\ \sim r \\ \downarrow \\ \vdots \end{array}$$

$$\begin{array}{c} p \\ \downarrow \\ \sim q \\ \downarrow \\ p \\ \downarrow \\ \sim q \\ \downarrow \\ \vdots \end{array}$$

DEFINITIONS: SUMMARY

- ▶ A justification frame contains a set of rules
- ▶ The rules determine which justifications are possible
- ▶ A branch evaluation determines which branches are “good”
- ▶ A justification is “good” if all its branches are “good”
- ▶ An interpretation is a **model** (according to some semantics, induced by the branch evaluation) if the truth value of each fact equals the value of its best justification

OUTLINE

1. Justification Theory: Motivation & Definitions
2. Two Flavours of Justifications
3. The Consistency Problem
4. The Proof
5. Conclusion

TWO DEFINITIONS OF JUSTIFICATIONS

Definition ([Den93, MBDH22])

Let $\mathbb{JF} = \langle \mathbb{F}, \mathbb{F}_d, R \rangle$ be a justification frame. A **(tree-like) justification** J in \mathbb{JF} is a labeled tree such that the set of children of each internal node is a case (rule) in R for that node.

Definition

([Mar09, DBS15, MPBD18, MBD21])

Let $\mathbb{JF} = \langle \mathbb{F}, \mathbb{F}_d, R \rangle$ be a justification frame. A **(graph-like) justification** J in \mathbb{JF} is a graph with nodes in \mathbb{F} such that the set of children of each internal node is a case (rule) in R for that node.

TWO DEFINITIONS OF JUSTIFICATIONS

Definition ([Den93, MBDH22])

Let $\mathbb{JF} = \langle \mathbb{F}, \mathbb{F}_d, R \rangle$ be a justification frame. A **(tree-like) justification** J in \mathbb{JF} is a labeled tree such that the set of children of each internal node is a case (rule) in R for that node.

Definition

([Mar09, DBS15, MPBD18, MBD21])

Let $\mathbb{JF} = \langle \mathbb{F}, \mathbb{F}_d, R \rangle$ be a justification frame. A **(graph-like) justification** J in \mathbb{JF} is a graph with nodes in \mathbb{F} such that the set of children of each internal node is a case (rule) in R for that node.

Theorem

Every graph-like justification J_g can be “unfolded” into a tree-like justification J_t such that $\text{val}_{\mathcal{B}}(J_t, x, I) \geq_t \text{val}_{\mathcal{B}}(J_g, x, I)$ for each x

THE GRAPH-REDUCIBILITY PROBLEM

Open Problem (The Graph-Reducibility Problem)

Under which conditions on \mathcal{B} can every tree-like justification J_t be “reduced” to a graph-like justification J_g with $\text{val}_{\mathcal{B}}(J_g, x, I) \geq_t \text{val}_{\mathcal{B}}(J_t, x, I)$?

First studied by Marynissen et al [MBD20].

THE GRAPH-REDUCIBILITY PROBLEM

Open Problem (The Graph-Reducibility Problem)

Under which conditions on \mathcal{B} can every tree-like justification J_t be “reduced” to a graph-like justification J_g with $\text{val}_{\mathcal{B}}(J_g, x, I) \geq_t \text{val}_{\mathcal{B}}(J_t, x, I)$?

First studied by Marynissen et al [MBD20].

Example

The branch evaluation \mathcal{B}_{ex} maps:

- ▶ finite branches to their last element
- ▶ infinite branches with a **consistent** positive tail to \mathbf{f}
- ▶ infinite branches with a **consistent** negative tail to \mathbf{t}
- ▶ other branches to \mathbf{u}

consistent branch:
whenever $x_i = x_j$ also
 $x_{i+1} = x_{j+1}$

THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

 $a \leftarrow b$ $a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$ $b \leftarrow a \quad \sim b \leftarrow \sim a$ $c \leftarrow a \quad \sim c \leftarrow \sim a$

 \mathcal{B}_{ex} maps:

- ▶ finite branch: last element
- ▶ **consistent** positive tail: **f**
- ▶ **consistent** negative tail: **t**
- ▶ other: **u**

THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

 $a \leftarrow b$ $a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$ $b \leftarrow a \quad \sim b \leftarrow \sim a$ $c \leftarrow a \quad \sim c \leftarrow \sim a$

Tree-like:

 \mathcal{B}_{ex} maps:

- ▶ finite branch: last element
- ▶ **consistent** positive tail: **f**
- ▶ **consistent** negative tail: **t**
- ▶ other: **u**

THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

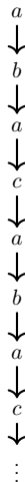
$$a \leftarrow b$$

$$a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$$

$$b \leftarrow a \quad \sim b \leftarrow \sim a$$

$$c \leftarrow a \quad \sim c \leftarrow \sim a$$

Tree-like:



 \mathcal{B}_{ex} maps:

- ▶ finite branch: last element
- ▶ **consistent** positive tail: **f**
- ▶ **consistent** negative tail: **t**
- ▶ other: **u**

THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

 $a \leftarrow b$ $a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$ $b \leftarrow a \quad \sim b \leftarrow \sim a$ $c \leftarrow a \quad \sim c \leftarrow \sim a$

Tree-like:

 \mathcal{B}_{ex} maps:

- ▶ finite branch: last element
- ▶ **consistent** positive tail: **f**
- ▶ **consistent** negative tail: **t**
- ▶ other: **u**

 $SV_t(a, I) = \mathbf{u}$

$$\begin{array}{c}
 a \\
 \downarrow \\
 b \\
 \downarrow \\
 a \\
 \downarrow \\
 c \\
 \downarrow \\
 a \\
 \downarrow \\
 b \\
 \downarrow \\
 a \\
 \downarrow \\
 c \\
 \downarrow \\
 \vdots
 \end{array}$$

THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

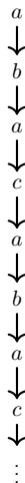
$$a \leftarrow b$$

$$a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$$

$$b \leftarrow a \quad \sim b \leftarrow \sim a$$

$$c \leftarrow a \quad \sim c \leftarrow \sim a$$

Tree-like:

 \mathcal{B}_{ex} maps:

- ▶ finite branch: last element
- ▶ consistent positive tail: **f**
- ▶ consistent negative tail: **t**
- ▶ other: **u**

$$\text{SV}_t(a, I) = \mathbf{u}$$

and

$$\text{SV}_t(\sim a, I) = \mathbf{u}$$

THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

 $a \leftarrow b$ $a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$ $b \leftarrow a \quad \sim b \leftarrow \sim a$ $c \leftarrow a \quad \sim c \leftarrow \sim a$

Tree-like:

 $SV_t(a, I) = \mathbf{u}$

and

 $SV_t(\sim a, I) = \mathbf{u}$

Graph-like:

$$\begin{array}{c}
 a \\
 \downarrow \\
 b \\
 \downarrow \\
 a \\
 \downarrow \\
 c \\
 \downarrow \\
 a \\
 \downarrow \\
 b \\
 \downarrow \\
 a \\
 \downarrow \\
 c \\
 \downarrow \\
 \vdots
 \end{array}$$
 \mathcal{B}_{ex} maps:

- ▶ finite branch: last element
- ▶ consistent positive tail: **f**
- ▶ consistent negative tail: **t**
- ▶ other: **u**

THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

$$a \leftarrow b$$

$$a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$$

$$b \leftarrow a \quad \sim b \leftarrow \sim a$$

$$c \leftarrow a \quad \sim c \leftarrow \sim a$$

\mathcal{B}_{ex} maps:

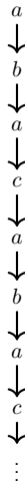
- ▶ finite branch: last element
- ▶ **consistent** positive tail: **f**
- ▶ **consistent** negative tail: **t**
- ▶ other: **u**

Tree-like:

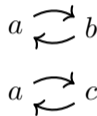
$$\text{SV}_t(a, I) = \mathbf{u}$$

and

$$\text{SV}_t(\sim a, I) = \mathbf{u}$$



Graph-like:



THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

$$a \leftarrow b$$

$$a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$$

$$b \leftarrow a \quad \sim b \leftarrow \sim a$$

$$c \leftarrow a \quad \sim c \leftarrow \sim a$$

\mathcal{B}_{ex} maps:

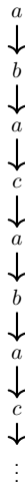
- ▶ finite branch: last element
- ▶ consistent positive tail: **f**
- ▶ consistent negative tail: **t**
- ▶ other: **u**

Tree-like:

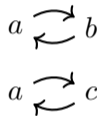
$$SV_t(a, I) = \mathbf{u}$$

and

$$SV_t(\sim a, I) = \mathbf{u}$$



Graph-like:



$$SV_g(a, I) = \mathbf{f}$$

THE GRAPH-REDUCIBILITY PROBLEM: EXAMPLE

$$a \leftarrow b$$

$$a \leftarrow c \quad \sim a \leftarrow \sim b, \sim c$$

$$b \leftarrow a \quad \sim b \leftarrow \sim a$$

$$c \leftarrow a \quad \sim c \leftarrow \sim a$$

\mathcal{B}_{ex} maps:

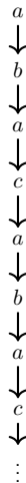
- ▶ finite branch: last element
- ▶ **consistent** positive tail: **f**
- ▶ **consistent** negative tail: **t**
- ▶ other: **u**

Tree-like:

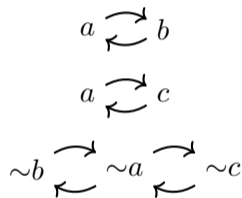
$$SV_t(a, I) = \mathbf{u}$$

and

$$SV_t(\sim a, I) = \mathbf{u}$$



Graph-like:



$$SV_g(a, I) = \mathbf{f}$$

and

$$SV_g(\sim a, I) = \mathbf{u}$$

TREE-LIKE AND GRAPH-LIKE JUSTIFICATIONS

- ▶ Our results are **only** about tree-like justifications

TREE-LIKE AND GRAPH-LIKE JUSTIFICATIONS

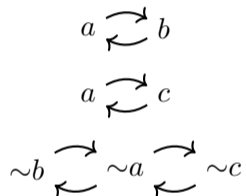
- ▶ Our results are **only** about tree-like justifications
- ▶ In examples, I might sometimes draw graph-like justifications, but mean their tree-unfolding

OUTLINE

1. Justification Theory: Motivation & Definitions
2. Two Flavours of Justifications
3. The Consistency Problem
4. The Proof
5. Conclusion

THE CONSISTENCY PROBLEM: EXAMPLE

Graph-like:

With “weird” \mathcal{B}_{ex} :

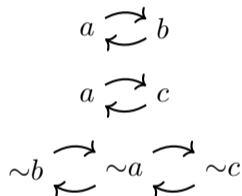
$$SV_g(a, I) = \mathbf{f}$$

while

$$SV_g(\sim a, I) = \mathbf{u}$$

THE CONSISTENCY PROBLEM: EXAMPLE

Graph-like:



► Explanation why a fact x is true? Justification for x

With “weird” \mathcal{B}_{ex} :

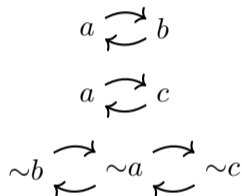
$$SV_g(a, I) = \mathbf{f}$$

while

$$SV_g(\sim a, I) = \mathbf{u}$$

THE CONSISTENCY PROBLEM: EXAMPLE

Graph-like:



- ▶ Explanation why a fact x is true? Justification for x
- ▶ Explanation why a fact x is false? Absence of a justification for x ?

With “weird” \mathcal{B}_{ex} :

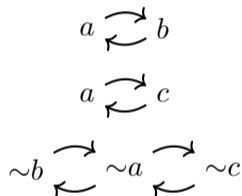
$$SV_g(a, I) = \mathbf{f}$$

while

$$SV_g(\sim a, I) = \mathbf{u}$$

THE CONSISTENCY PROBLEM: EXAMPLE

Graph-like:



- ▶ Explanation why a fact x is true? Justification for x
- ▶ Explanation why a fact x is false? Absence of a justification for x ? Justification for $\sim x$?

With “weird” \mathcal{B}_{ex} :

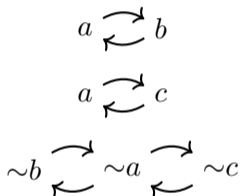
$$SV_g(a, I) = \mathbf{f}$$

while

$$SV_g(\sim a, I) = \mathbf{u}$$

THE CONSISTENCY PROBLEM: EXAMPLE

Graph-like:

With “weird” \mathcal{B}_{ex} :

$$SV_g(a, I) = \mathbf{f}$$

while

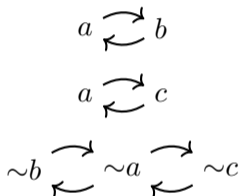
$$SV_g(\sim a, I) = \mathbf{u}$$

- ▶ Explanation why a fact x is true? Justification for x
- ▶ Explanation why a fact x is false? Absence of a justification for x ? Justification for $\sim x$?
- ▶ Here, $SV_g(a, I) \neq \sim SV_g(\sim a, I)$. Even though $SV_g(a, I) = \mathbf{f}$, there is no justification for the fact that a must be false ($\sim a$ must be true).

Can it be so that $SV(x) >_t \sim SV(\sim x)$?

THE CONSISTENCY PROBLEM: EXAMPLE

Graph-like:

With “weird” \mathcal{B}_{ex} :

$$SV_g(a, I) = \mathbf{f}$$

while

$$SV_g(\sim a, I) = \mathbf{u}$$

- ▶ Explanation why a fact x is true? Justification for x
- ▶ Explanation why a fact x is false? Absence of a justification for x ? Justification for $\sim x$?
- ▶ Here, $SV_g(a, I) \neq \sim SV_g(\sim a, I)$. Even though $SV_g(a, I) = \mathbf{f}$, there is no justification for the fact that a must be false ($\sim a$ must be true).

Can it be so that $SV(x) >_t \sim SV(\sim x)$? This would be problematic, it would mean we can explain both a and $\sim a$.

Theorem (Easy — tree-like and graph-like)

Under reasonable assumptions, $SV(x) \leq_t \sim SV(\sim x)$ for all x .

REASONABLE ASSUMPTIONS

- ▶ Set of rules is **complementary**

Definition (Complementary — various other characterizations exist)

We call \mathbb{JF} **complementary** if for every $x \in \mathbb{F}_d$:

1. for every selection function s for x , there exists an $A \in \mathbb{JF}(\sim x)$ with $A \subseteq \sim \text{Im}(s)$;
2. for every $A \in \mathbb{JF}(x)$, there exists a selection function s for $\sim x$ in R with $\sim \text{Im}(s) \subseteq A$.

- ▶ Branch evaluation **respects negation**

Without these conditions, we are in the wild.

REASONABLE ASSUMPTIONS

- ▶ Set of rules is **complementary**

Definition (Complementary — various other characterizations exist)

We call \mathbb{JF} **complementary** if for every $x \in \mathbb{F}_d$:

1. for every selection function s for x , there exists an $A \in \mathbb{JF}(\sim x)$ with $A \subseteq \sim \text{Im}(s)$;
2. for every $A \in \mathbb{JF}(x)$, there exists a selection function s for $\sim x$ in R with $\sim \text{Im}(s) \subseteq A$.

- ▶ Branch evaluation **respects negation**

Definition

A branch evaluation \mathcal{B} **respects negation** if $\mathcal{B}(\sim \mathbf{b}) = \sim \mathcal{B}(\mathbf{b})$ for each branch \mathbf{b} .

Without these conditions, we are in the wild.

THE CONSISTENCY PROBLEM

Definition

\mathbb{JS} is (tree/graph-like) **consistent** if $SV(\sim x, I) = \sim SV(x, I)$ for every x, I

THE CONSISTENCY PROBLEM

Definition

\mathbb{JS} is (tree/graph-like) **consistent** if $SV(\sim x, I) = \sim SV(x, I)$ for every x, I

Open Question (The Consistency Problem)

When is a justification system consistent? In particular, what properties do branch evaluations and justification frames need to have to ensure that the justification system is consistent?

THE CONSISTENCY PROBLEM

Definition

\mathbb{JS} is (tree/graph-like) **consistent** if $SV(\sim x, I) = \sim SV(x, I)$ for every x, I

Open Question (The Consistency Problem)

When is a justification system consistent? In particular, what properties do branch evaluations and justification frames need to have to ensure that the justification system is consistent?

Theorem (Our Result)

Every reasonable^() justification system is tree-like consistent.*

() Rules are complementary, and branch evaluation respects negation.*

THE CONSISTENCY PROBLEM: HISTORY

- ▶ **Tree-like**: completion, stable, and well-founded branch evaluations are consistent [Den93]

THE CONSISTENCY PROBLEM: HISTORY

- ▶ **Tree-like**: completion, stable, and well-founded branch evaluations are consistent [Den93]
- ▶ **Graph-like**: three above and Kripke-Kleene branch evaluation are consistent [MPBD18]
(also: first example of graph-like system that is not consistent)

THE CONSISTENCY PROBLEM: HISTORY

- ▶ **Tree-like**: completion, stable, and well-founded branch evaluations are consistent [Den93]
- ▶ **Graph-like**: three above and Kripke-Kleene branch evaluation are consistent [MPBD18]
(also: first example of graph-like system that is not consistent)
- ▶ **Graph- and tree-like**: Sufficient conditions for consistency of **finite** systems [MBD20]

THE CONSISTENCY PROBLEM: HISTORY

- ▶ **Tree-like**: completion, stable, and well-founded branch evaluations are consistent [Den93]
- ▶ **Graph-like**: three above and Kripke-Kleene branch evaluation are consistent [MPBD18]
(also: first example of graph-like system that is not consistent)
- ▶ **Graph- and tree-like**: Sufficient conditions for consistency of **finite** systems [MBD20]
- ▶ Graph-like **consistency** implies **graph-reducibility** (and tree-like consistency) [MBD20]

OUTLINE

1. Justification Theory: Motivation & Definitions
2. Two Flavours of Justifications
3. The Consistency Problem
4. The Proof
5. Conclusion

PROOF: CORE IDEA

- ▶ Assume $SV(x) \leq_t v$; we will construct a justification that shows $SV(\sim x) \geq_t \sim v$.

PROOF: CORE IDEA

- ▶ Assume $SV(x) \leq_t v$; we will construct a justification that shows $SV(\sim x) \geq_t \sim v$.
- ▶ Each justification for x has a branch with value at most v

PROOF: CORE IDEA

- ▶ Assume $SV(x) \leq_t v$; we will construct a justification that shows $SV(\sim x) \geq_t \sim v$.
- ▶ Each justification for x has a branch with value at most v
- ▶ Consider the set \mathbb{B} of all such branches

PROOF: CORE IDEA

- ▶ Assume $SV(x) \leq_t v$; we will construct a justification that shows $SV(\sim x) \geq_t \sim v$.
- ▶ Each justification for x has a branch with value at most v
- ▶ Consider the set \mathbb{B} of all such branches
- ▶ Construct (using **complementarity**) a justification J' for $\sim x$ such that **all** of its branches are in $\sim\mathbb{B}$

PROOF: CORE IDEA

- ▶ Assume $SV(x) \leq_t v$; we will construct a justification that shows $SV(\sim x) \geq_t \sim v$.
- ▶ Each justification for x has a branch with value at most v
- ▶ Consider the set \mathbb{B} of all such branches
- ▶ Construct (using **complementarity**) a justification J' for $\sim x$ such that **all** of its branches are in $\sim\mathbb{B}$
- ▶ Since \mathcal{B} **respects negation** the value of each branch in J' is at least $\sim v$.

PROOF: BASIS

Definition

A **branch selection** for x in \mathbb{JF} is a set \mathbb{B} of branches starting in x such that for each locally complete justification J rooted in x , \mathbb{B} contains at least one J -branch.

Lemma

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^ \in A$ such that for every justification $J_{y^*} \in \mathfrak{J}(y^*)$ rooted in y^* , \mathbb{B} contains at least one branch of the form $x \rightarrow y^* \rightarrow \mathbf{b}$ with $y^* \rightarrow \mathbf{b}$ a branch starting from the root of J_{y^*} .*

PROOF: BASIS

Definition

A **branch selection** for x in \mathbb{JF} is a set \mathbb{B} of branches starting in x such that for each locally complete justification J rooted in x , \mathbb{B} contains at least one J -branch.

Lemma

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^ \in A$ such that for every justification $J_{y^*} \in \mathfrak{J}(y^*)$ rooted in y^* , \mathbb{B} contains at least one branch of the form $x \rightarrow y^* \rightarrow \mathbf{b}$ with $y^* \rightarrow \mathbf{b}$ a branch starting from the root of J_{y^*} .*

Suppose towards contradiction that this does not hold

PROOF: BASIS

Definition

A **branch selection** for x in \mathbb{JF} is a set \mathbb{B} of branches starting in x such that for each locally complete justification J rooted in x , \mathbb{B} contains at least one J -branch.

Lemma

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^ \in A$ such that for every justification $J_{y^*} \in \mathfrak{J}(y^*)$ rooted in y^* , \mathbb{B} contains at least one branch of the form $x \rightarrow y^* \rightarrow \mathbf{b}$ with $y^* \rightarrow \mathbf{b}$ a branch starting from the root of J_{y^*} .*

Suppose towards contradiction that this does not hold

This means for each $y \in A$, there is a J_y such that \mathbb{B} chooses no branch in J_y (after cutting off the first x)

PROOF: BASIS

Definition

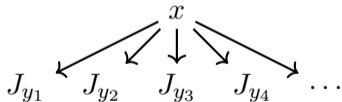
A **branch selection** for x in \mathbb{JF} is a set \mathbb{B} of branches starting in x such that for each locally complete justification J rooted in x , \mathbb{B} contains at least one J -branch.

Lemma

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that for every justification $J_{y^*} \in \mathfrak{J}(y^*)$ rooted in y^* , \mathbb{B} contains at least one branch of the form $x \rightarrow y^* \rightarrow \mathbf{b}$ with $y^* \rightarrow \mathbf{b}$ a branch starting from the root of J_{y^*} .

Suppose towards contradiction that this does not hold

This means for each $y \in A$, there is a J_y such that \mathbb{B} chooses no branch in J_y (after cutting off the first x)



PROOF: BASIS

Definition

A **branch selection** for x in \mathbb{JF} is a set \mathbb{B} of branches starting in x such that for each locally complete justification J rooted in x , \mathbb{B} contains at least one J -branch.

Lemma

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that for every justification $J_{y^*} \in \mathfrak{J}(y^*)$ rooted in y^* , \mathbb{B} contains at least one branch of the form $x \rightarrow y^* \rightarrow \mathbf{b}$ with $y^* \rightarrow \mathbf{b}$ a branch starting from the root of J_{y^*} .

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .

THE PROOF

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^ \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .*

THE PROOF

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .

Corollary

If \mathbb{JS} is complementary and \mathbb{B} is a branch selection for x , then there is a rule $\sim x \leftarrow B_{\sim x}$ such that for each $y \in \sim B_{\sim x}$, $\mathbb{B}_y := \{y \rightarrow \mathbf{b} \mid x \rightarrow y \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y .

THE PROOF

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^ \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .*

Corollary

If \mathbb{JS} is complementary and \mathbb{B} is a branch selection for x , then there is a rule $\sim x \leftarrow B_{\sim x}$ such that for each $y \in \sim B_{\sim x}$, $\mathbb{B}_y := \{y \rightarrow \mathbf{b} \mid x \rightarrow y \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y .

Idea of the proof of the main theorem:

THE PROOF

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .

Corollary

If \mathbb{JS} is complementary and \mathbb{B} is a branch selection for x , then there is a rule $\sim x \leftarrow B_{\sim x}$ such that for each $y \in \sim B_{\sim x}$, $\mathbb{B}_y := \{y \rightarrow \mathbf{b} \mid x \rightarrow y \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y .

Idea of the proof of the main theorem:

- ▶ Given a branch selection for x , construct a justification for $\sim x$. How?

THE PROOF

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .

Corollary

If \mathbb{JS} is complementary and \mathbb{B} is a branch selection for x , then there is a rule $\sim x \leftarrow B_{\sim x}$ such that for each $y \in \sim B_{\sim x}$, $\mathbb{B}_y := \{y \rightarrow \mathbf{b} \mid x \rightarrow y \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y .

Idea of the proof of the main theorem:

- ▶ Given a branch selection for x , construct a justification for $\sim x$. How?
- ▶ Choose a rule $\sim x \leftarrow B_{\sim x}$ using corollary.

THE PROOF

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .

Corollary

If \mathbb{JS} is complementary and \mathbb{B} is a branch selection for x , then there is a rule $\sim x \leftarrow B_{\sim x}$ such that for each $y \in \sim B_{\sim x}$, $\mathbb{B}_y := \{y \rightarrow \mathbf{b} \mid x \rightarrow y \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y .

Idea of the proof of the main theorem:

- ▶ Given a branch selection for x , construct a justification for $\sim x$. How?
- ▶ Choose a rule $\sim x \leftarrow B_{\sim x}$ using corollary.
- ▶ For each $\sim y \in B_{\sim x}$ we have an induced branch evaluation for y .

THE PROOF

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .

Corollary

If \mathbb{JS} is complementary and \mathbb{B} is a branch selection for x , then there is a rule $\sim x \leftarrow B_{\sim x}$ such that for each $y \in \sim B_{\sim x}$, $\mathbb{B}_y := \{y \rightarrow \mathbf{b} \mid x \rightarrow y \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y .

Idea of the proof of the main theorem:

- ▶ Given a branch selection for x , construct a justification for $\sim x$. How?
- ▶ Choose a rule $\sim x \leftarrow B_{\sim x}$ using corollary.
- ▶ For each $\sim y \in B_{\sim x}$ we have an induced branch evaluation for y .
- ▶ Repeat this process

THE PROOF

Corollary

Let \mathbb{B} be a branch selection for x , and let $x \leftarrow A$ be a rule in \mathbb{JF} . There exists a $y^* \in A$ such that $\mathbb{B}_{y^*} := \{y^* \rightarrow \mathbf{b} \mid x \rightarrow y^* \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y^* .

Corollary

If \mathbb{JS} is complementary and \mathbb{B} is a branch selection for x , then there is a rule $\sim x \leftarrow B_{\sim x}$ such that for each $y \in \sim B_{\sim x}$, $\mathbb{B}_y := \{y \rightarrow \mathbf{b} \mid x \rightarrow y \rightarrow \mathbf{b} \in \mathbb{B}\}$ is a branch selection for y .

Idea of the proof of the main theorem:

- ▶ Given a branch selection for x , construct a justification for $\sim x$. How?
- ▶ Choose a rule $\sim x \leftarrow B_{\sim x}$ using corollary.
- ▶ For each $\sim y \in B_{\sim x}$ we have an induced branch evaluation for y .
- ▶ Repeat this process

Actual proof.... a bit finicky, but this is the gist

OUTLINE

1. Justification Theory: Motivation & Definitions
2. Two Flavours of Justifications
3. The Consistency Problem
4. The Proof
5. Conclusion

CONCLUSION

- ▶ **Consistency** relates the absence of an explanation for x to the existence of an explanation for $\sim x$.

CONCLUSION

- ▶ **Consistency** relates the absence of an explanation for x to the existence of an explanation for $\sim x$.
- ▶ We have once and for all resolved this for tree-like justifications

CONCLUSION

- ▶ **Consistency** relates the absence of an explanation for x to the existence of an explanation for $\sim x$.
- ▶ We have once and for all resolved this for tree-like justifications
- ▶ No new results for the most common branch evaluations (they were known to be consistent)

CONCLUSION

- ▶ **Consistency** relates the absence of an explanation for x to the existence of an explanation for $\sim x$.
- ▶ We have once and for all resolved this for tree-like justifications
- ▶ No new results for the most common branch evaluations (they were known to be consistent)
- ▶ New results for all future branch evaluations (e.g. those coming from nested justifications; see next talk)

CONCLUSION

- ▶ **Consistency** relates the absence of an explanation for x to the existence of an explanation for $\sim x$.
- ▶ We have once and for all resolved this for tree-like justifications
- ▶ No new results for the most common branch evaluations (they were known to be consistent)
- ▶ New results for all future branch evaluations (e.g. those coming from nested justifications; see next talk)

Open Question

*Under which conditions are branch evaluations graph-like consistent?
(equivalently): Under which conditions are branch evaluations graph-reducible?*

CONCLUSION

- ▶ **Consistency** relates the absence of an explanation for x to the existence of an explanation for $\sim x$.
- ▶ We have once and for all resolved this for tree-like justifications
- ▶ No new results for the most common branch evaluations (they were known to be consistent)
- ▶ New results for all future branch evaluations (e.g. those coming from nested justifications; see next talk)

Open Question

*Under which conditions are branch evaluations graph-like consistent?
(equivalently): Under which conditions are branch evaluations graph-reducible?*

CONCLUSION

- ▶ **Consistency** relates the absence of an explanation for x to the existence of an explanation for $\sim x$.
- ▶ We have once and for all resolved this for tree-like justifications
- ▶ No new results for the most common branch evaluations (they were known to be consistent)
- ▶ New results for all future branch evaluations (e.g. those coming from nested justifications; see next talk)

Open Question

*Under which conditions are branch evaluations graph-like consistent?
(equivalently): Under which conditions are branch evaluations graph-reducible?*

Interested? I'm looking for good postdocs/PhD students

Thanks for your attention!

REFERENCES

- [DBS15] Marc Denecker, Gerhard Brewka, and Hannes Strass. *A formal theory of justifications*. In Francesco Calimeri, Giovambattista Ianni, and Mirosław Truszczyński, editors, *Logic Programming and Nonmonotonic Reasoning - 13th International Conference, LPNMR 2015, Lexington, KY, USA, September 27-30, 2015. Proceedings*, volume 9345 of *Lecture Notes in Computer Science*, pages 250–264. Springer, 2015.
- [Den93] Marc Denecker. *Knowledge representation and reasoning in incomplete logic programming*. PhD thesis, K.U.Leuven, Leuven, Belgium, September 1993.
- [Mar09] Maarten Mariën. *Model Generation for ID-Logic*. PhD thesis, Department of Computer Science, KU Leuven, Belgium, February 2009.
- [MBD20] Simon Marynissen, Bart Bogaerts, and Marc Denecker. *Exploiting game theory for analysing justifications*. *Theory Pract. Log. Program.*, 20(6):880–894, 2020.
- [MBD21] Simon Marynissen, Bart Bogaerts, and Marc Denecker. *On the relation between approximation fixpoint theory and justification theory*. In Zhi-Hua Zhou, editor, *Proceedings of the Thirtieth International Joint Conference on Artificial Intelligence, IJCAI 2021, Virtual Event / Montreal, Canada, 19-27 August 2021*, pages 1973–1980. ijcai.org, 2021.

REFERENCES

- [MBDH22] Simon Marynissen, Bart Bogaerts, Marc Denecker, and Jesse Heyninck. *On nested justification systems*. *Theory Pract. Log. Program.*, 22, 2022. To appear (Accepted for ICLP 2022 special issue in TPLP).
- [MPBD18] Simon Marynissen, Niko Passchyn, Bart Bogaerts, and Marc Denecker. *Consistency in justification theory*. In *Proceedings of 17th International Workshop on Non-Monotonic Reasoning (NMR 2018), Tempe, Arizona, USA, Oct. 27-29, 2018*, pages 41–52. AAAI Press 2018, 2018.